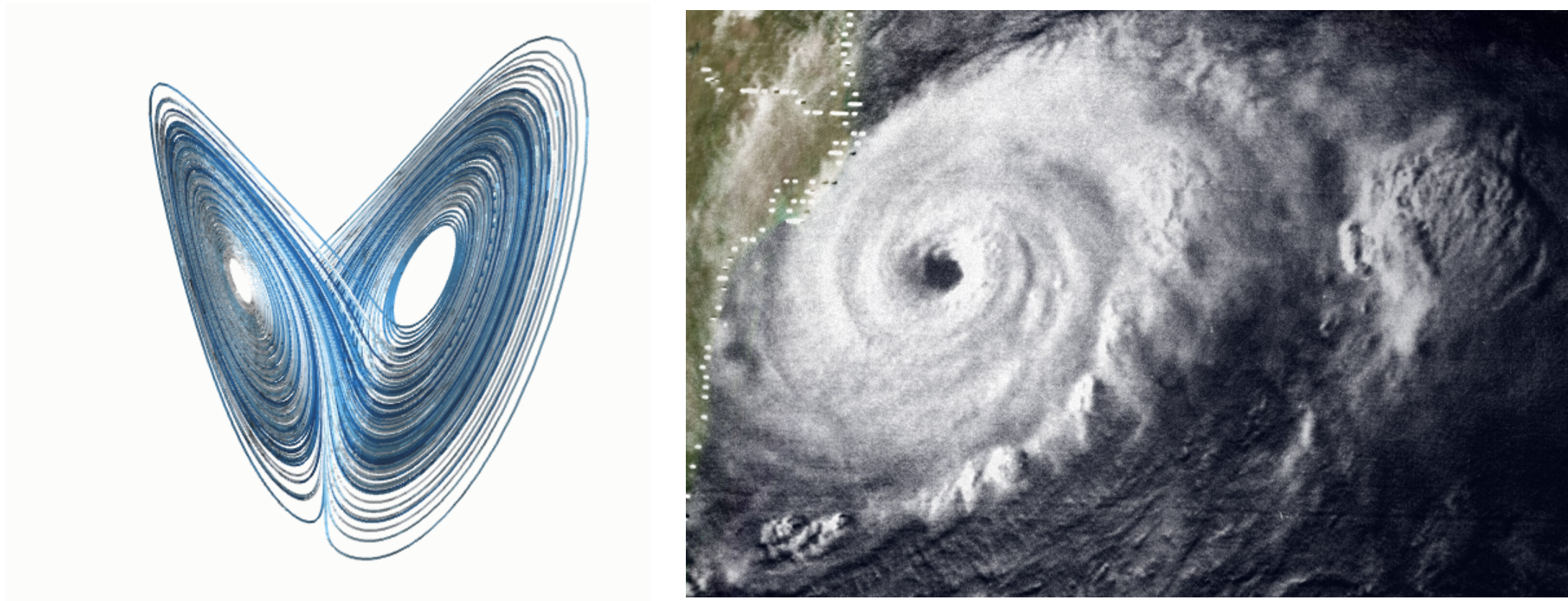


Predictability of wall-bounded flows by massive ensemble forecasting

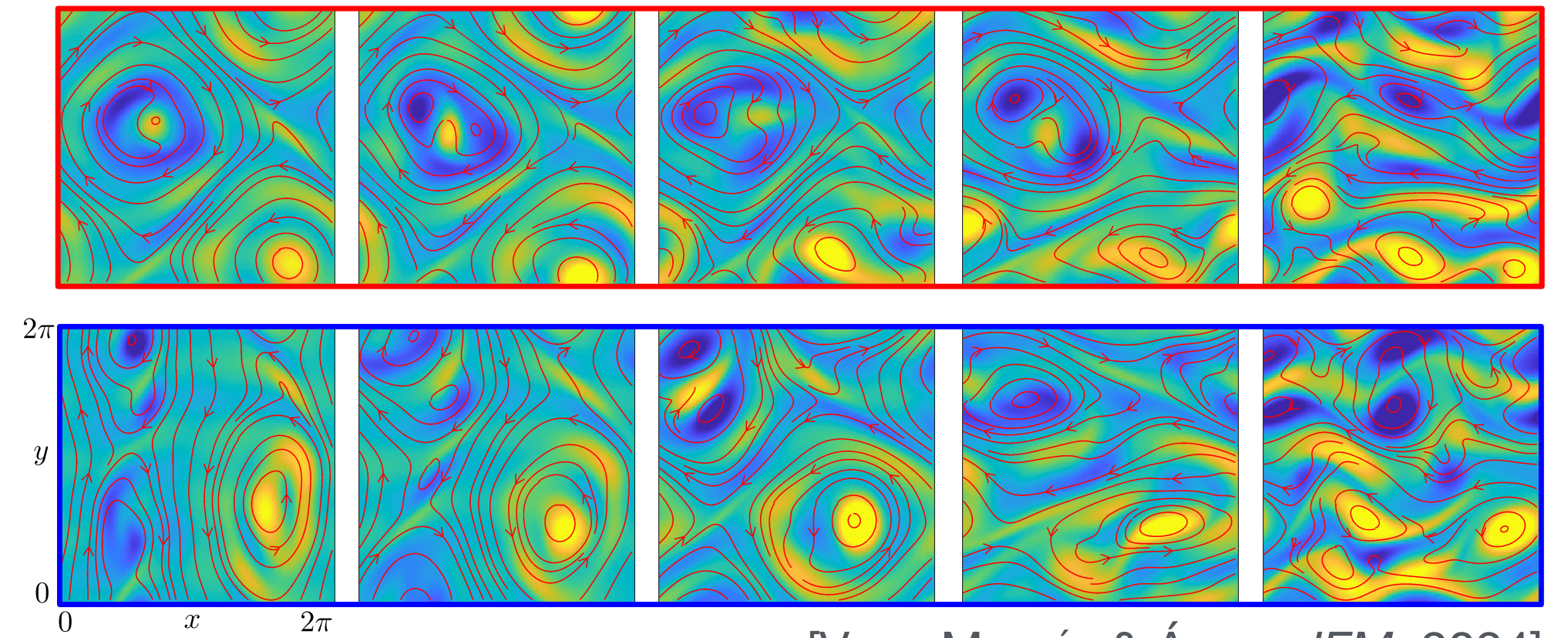
Alberto Vela-Martín¹ & Miguel P. Encinar¹

Predictability of Turbulent Flows

Chaos



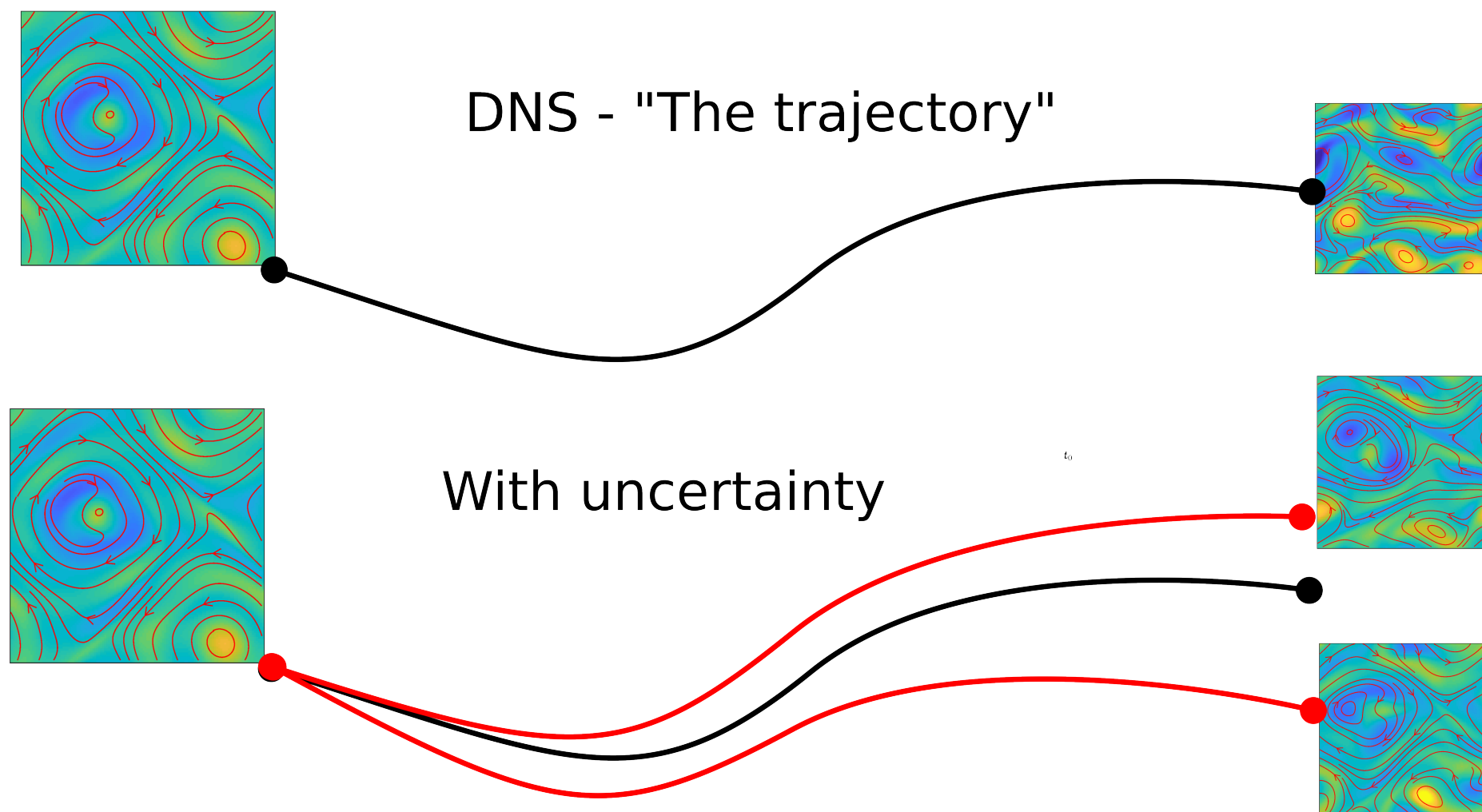
Extreme Events



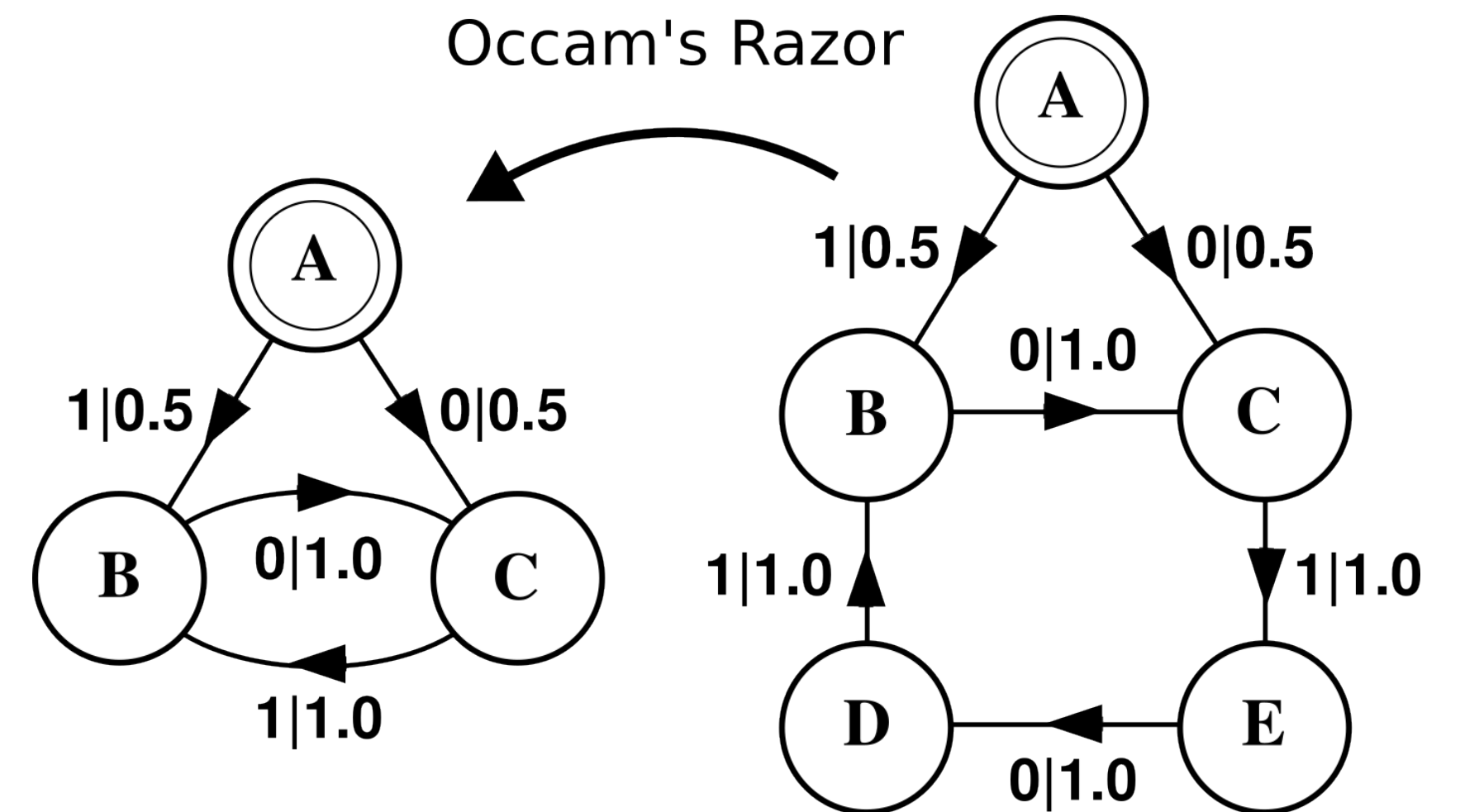
[VELA-MARTÍN & ÁVILA, *JFM*, 2024]

Initial condition

Prediction

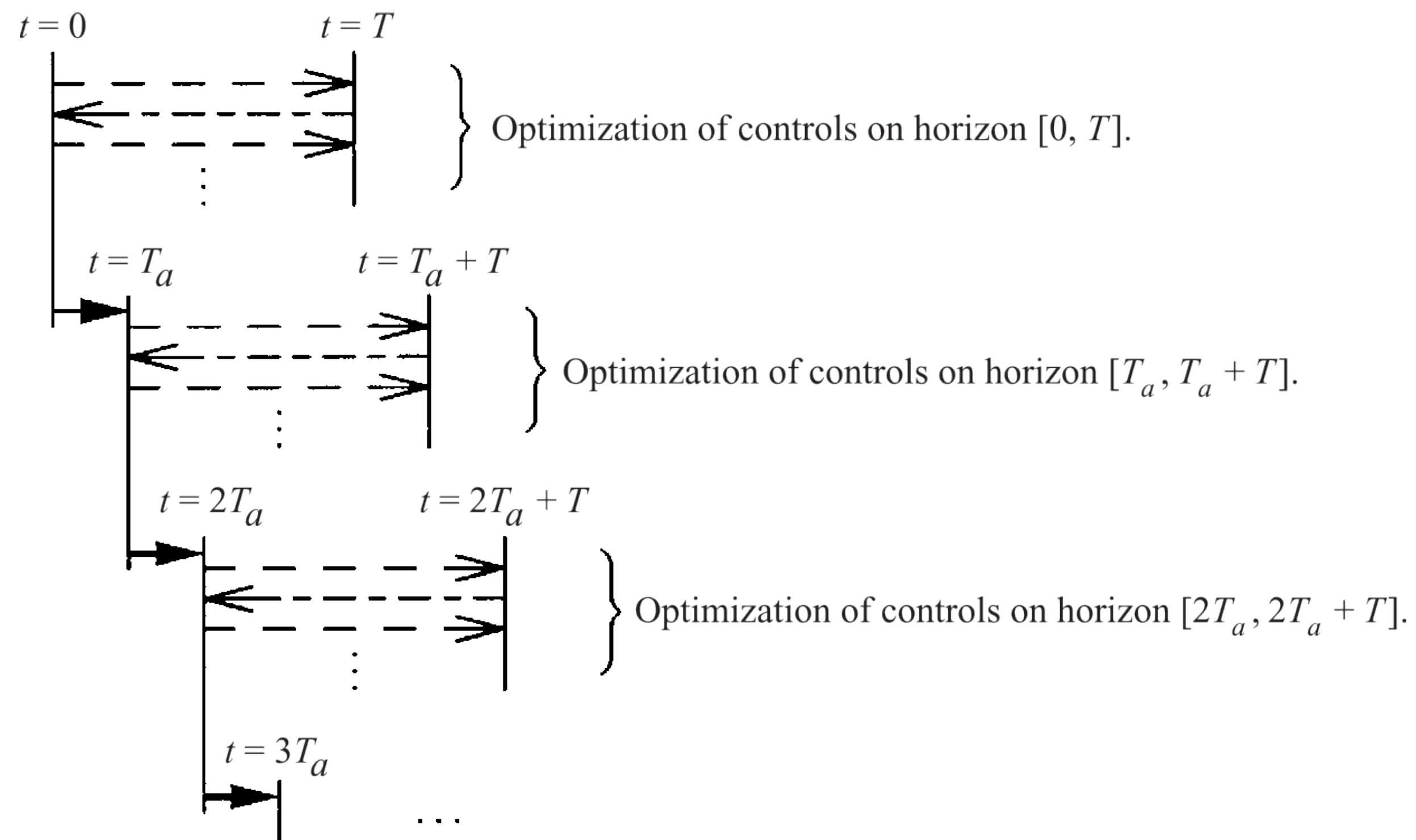


Optimal Predictive Models



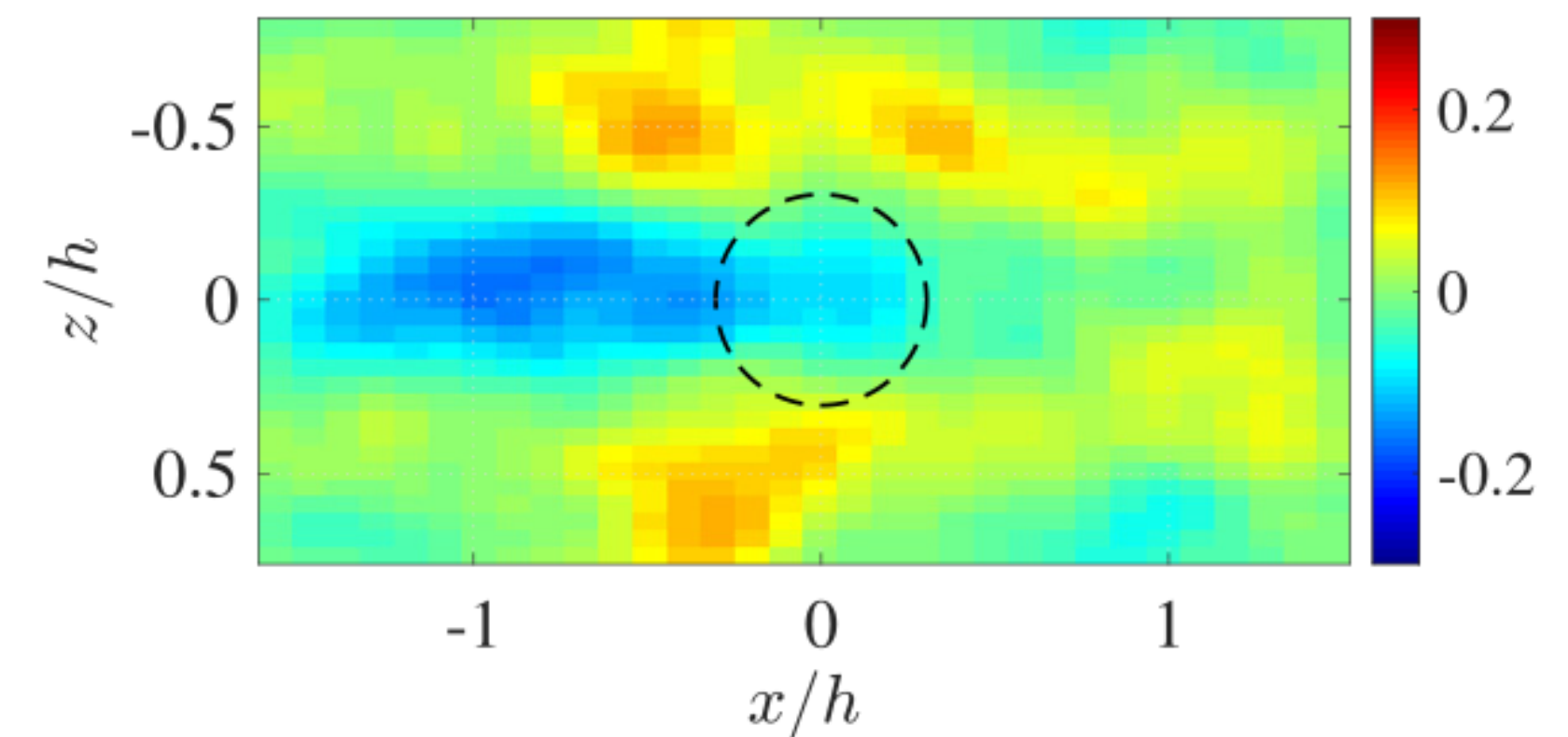
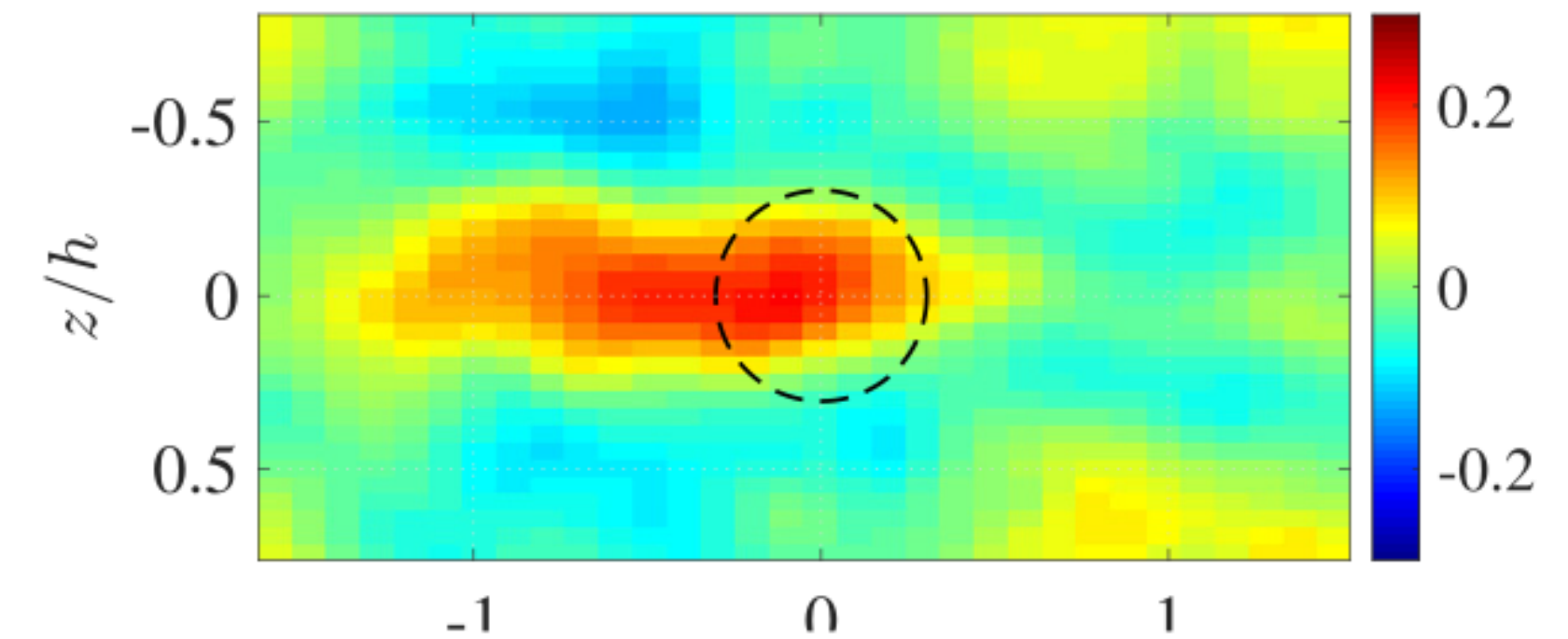
Implications for Control

Optimal Predictive Control



[BEWLEY ET AL, *JFM*, 2001]

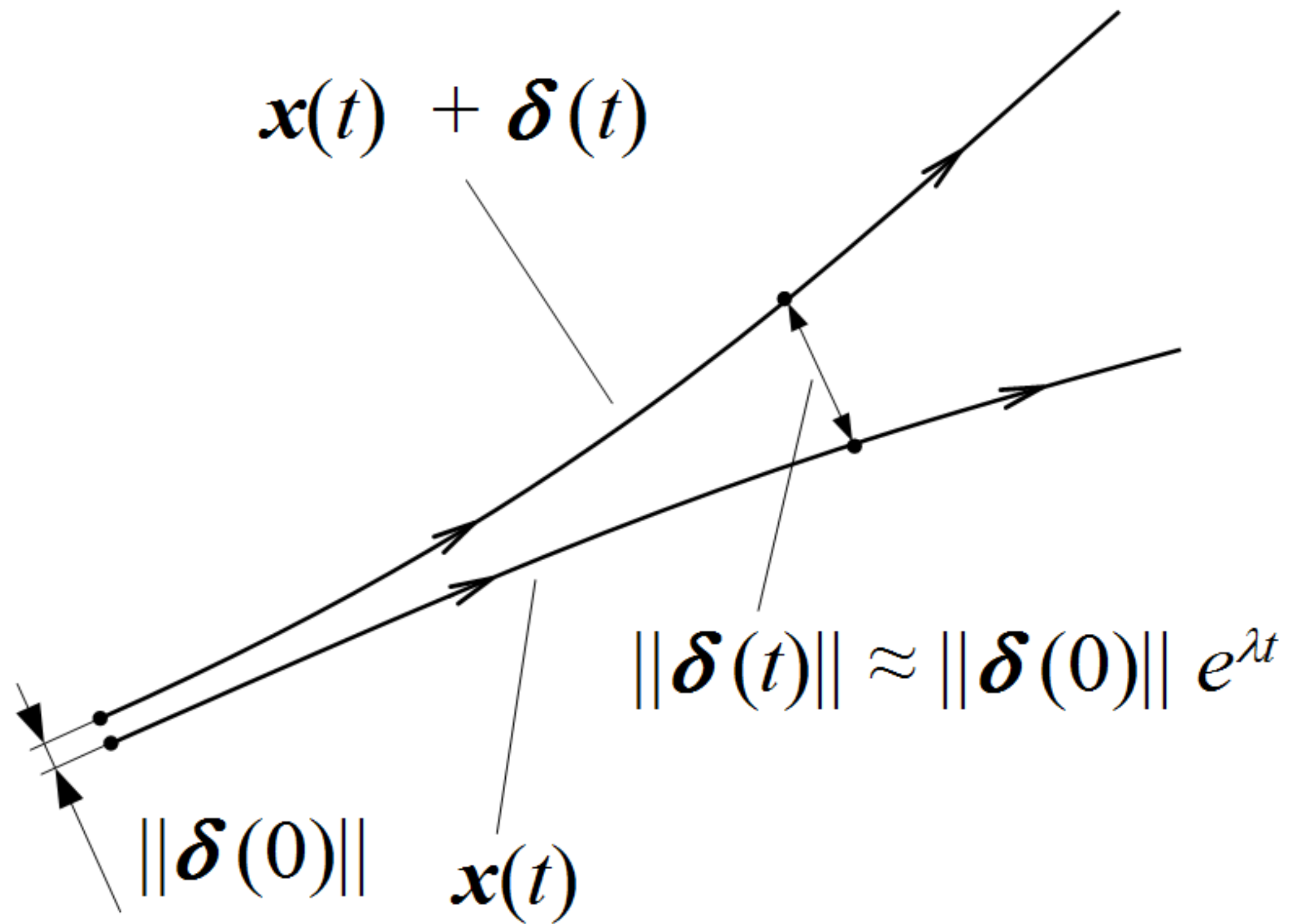
Monte-Carlo Control



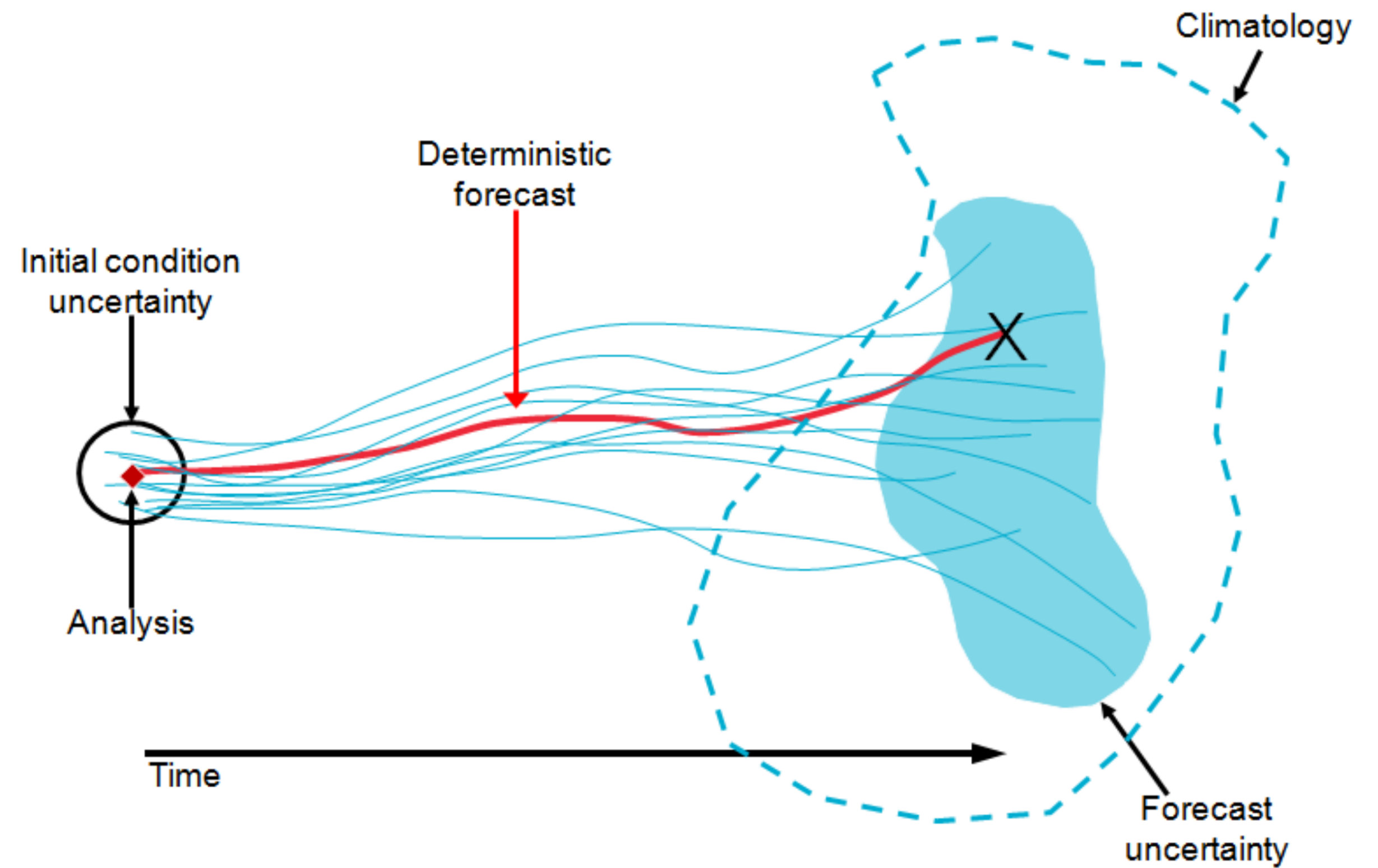
[PASTOR ET AL., *JPCS*, 2020]

How to measure predictability and uncertainty growth

Lyapunov Exponents

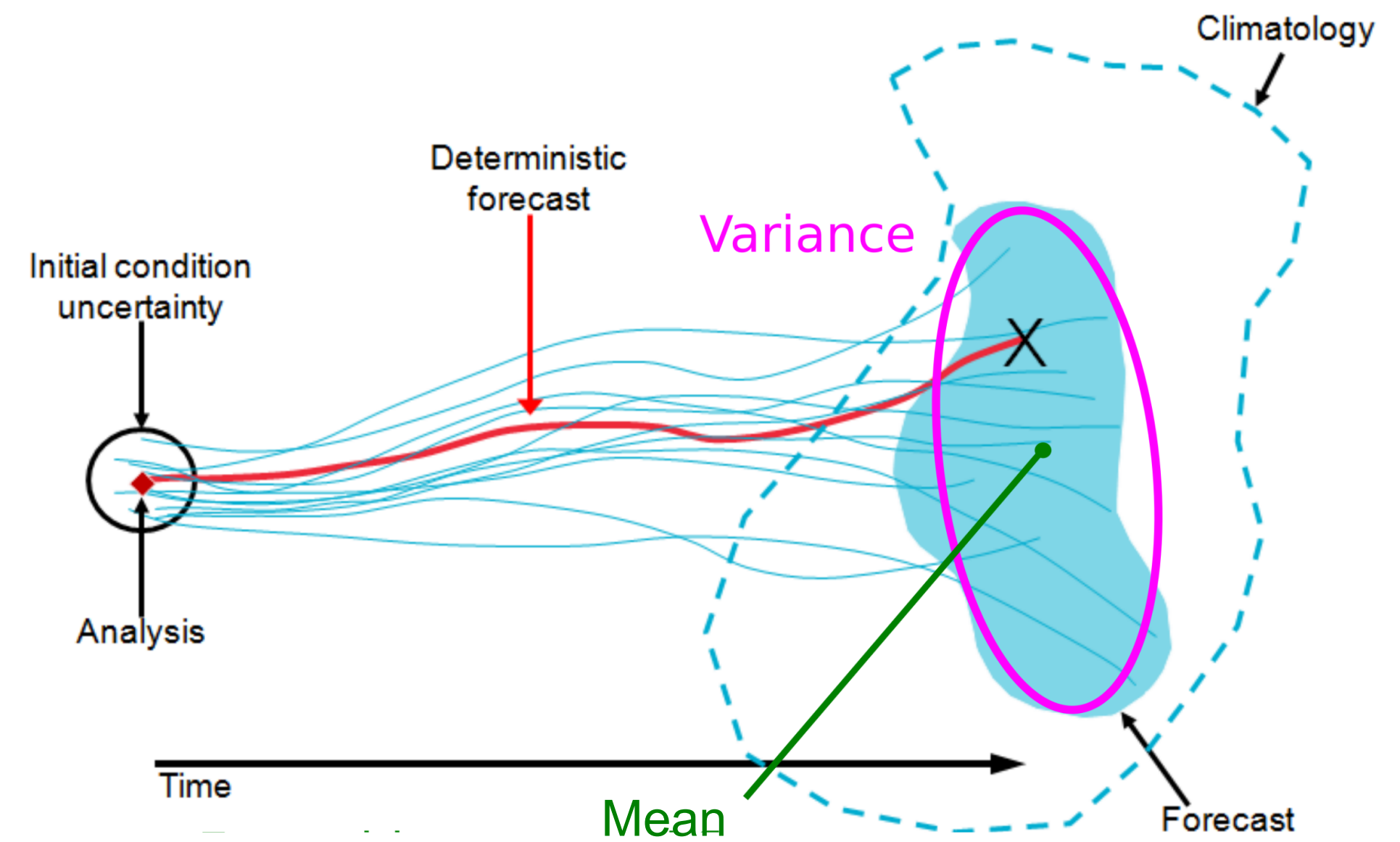


Ensemble Forecasting

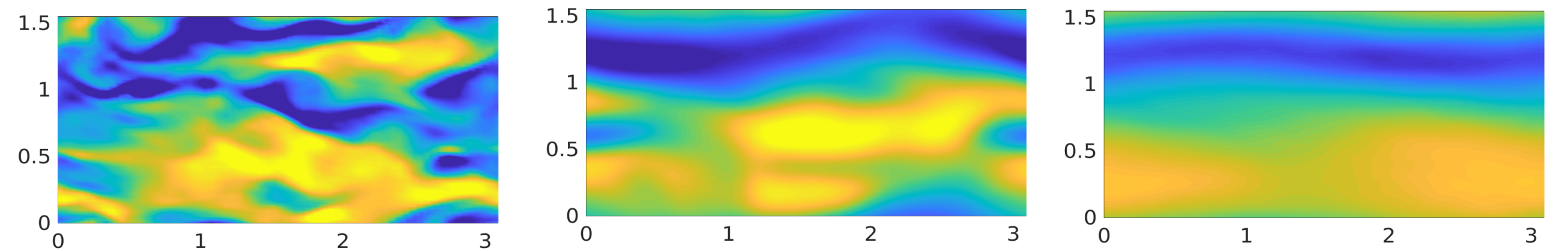


Massive ensemble forecasting of turbulent channel flow

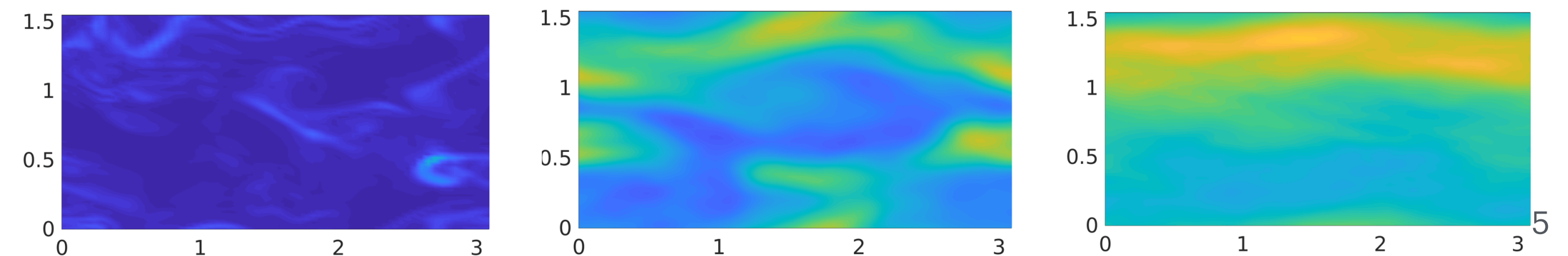
- ‘Lyapunov’ ensembles— Small initial perturbation
- Ensembles with 1024 **DNSs** (trajectories)
- $Re_\tau = 180$, small box ($\pi \times \pi/2$)
- **96** initial base flows (100 000 simulations)
- Ensemble-averaged flow field— **Optimal prediction** in the least squared sense
- Unpredictable flow patterns are **filtered out**



Ensemble averaged streamwise velocity fluctuations



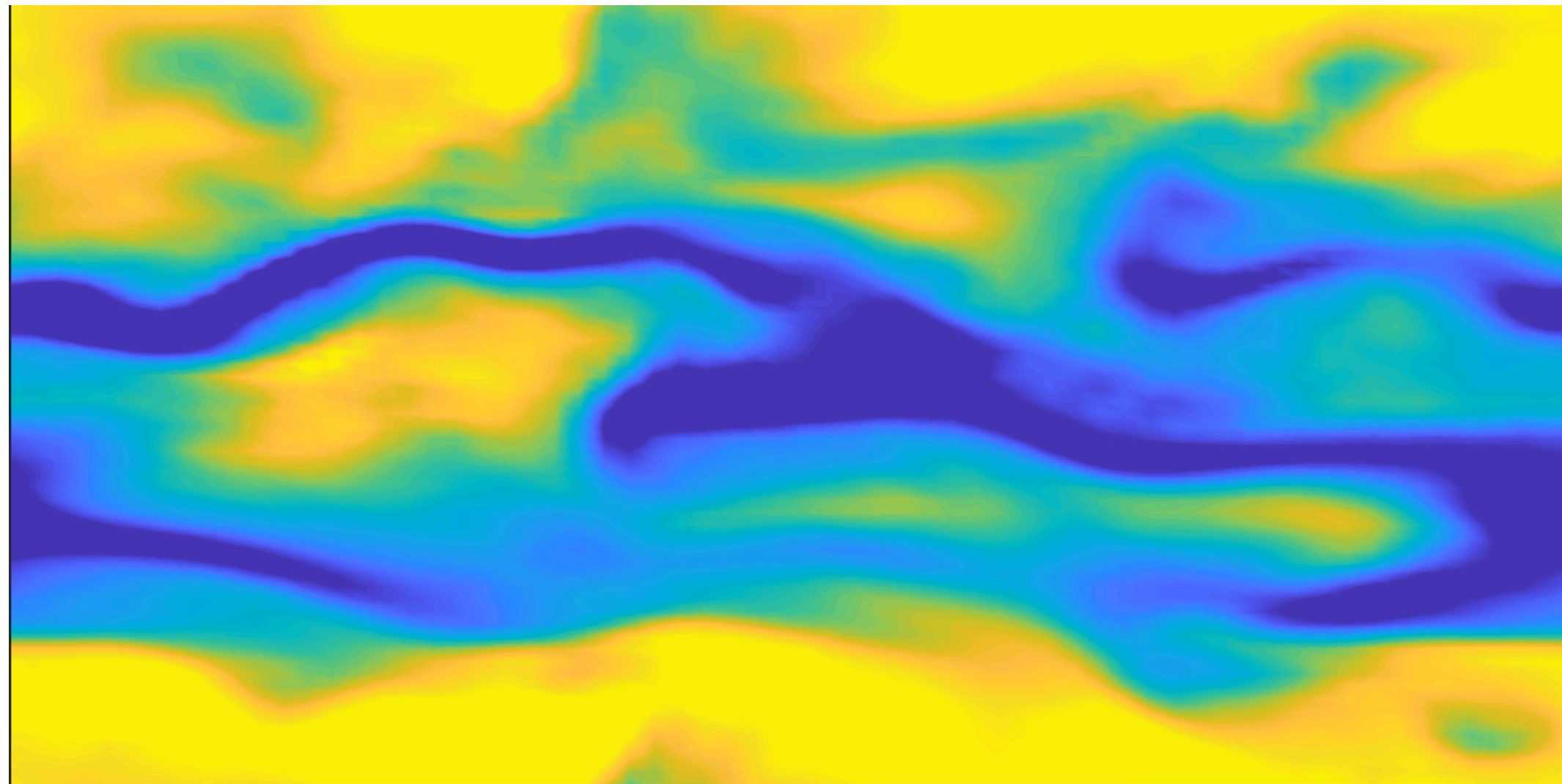
Ensemble variance streamwise velocity fluctuations



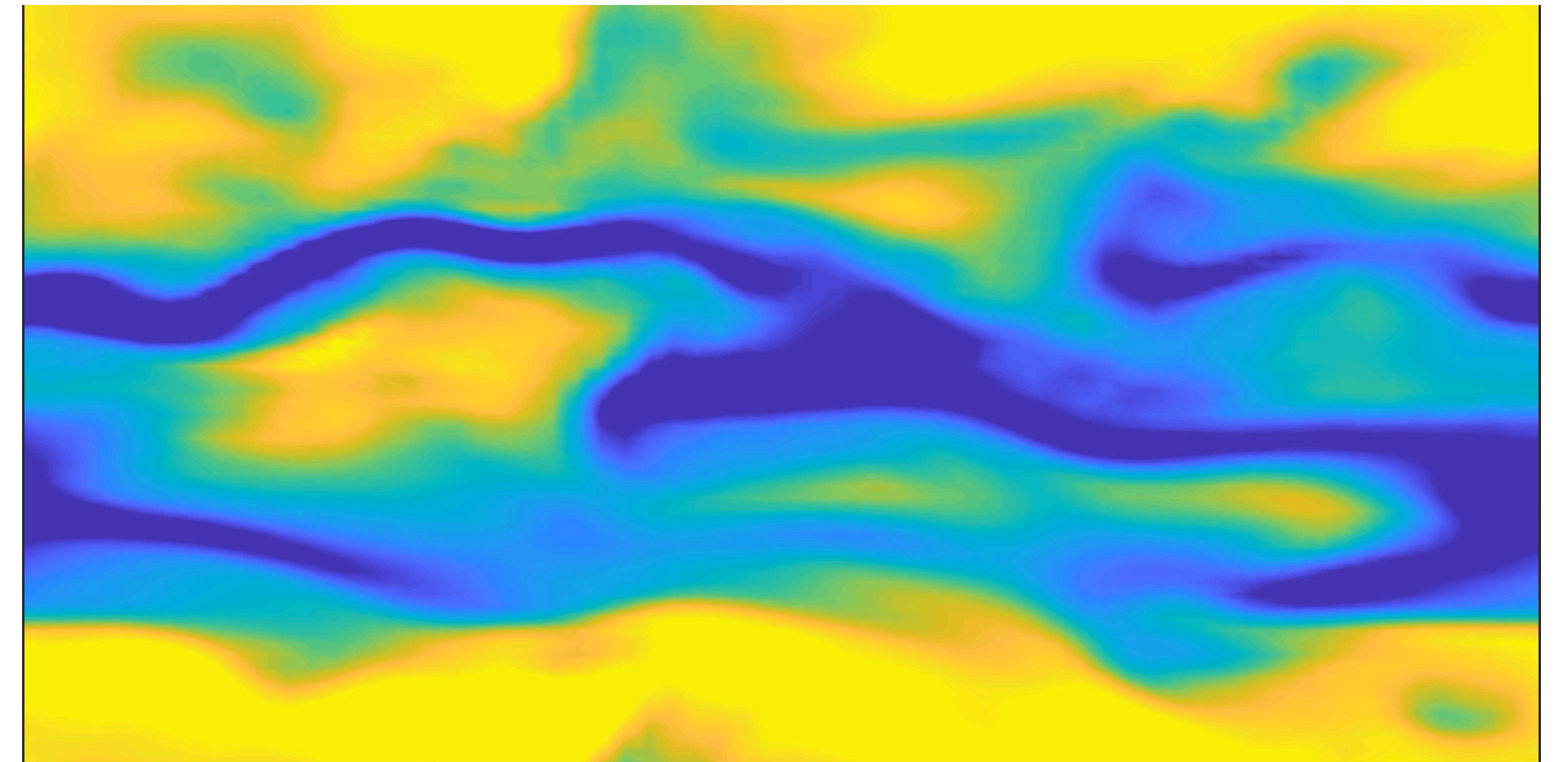
How does it look like?

Video of u of simulation #1 out of #96 at $y^+ \approx 50$

Base Trajectory

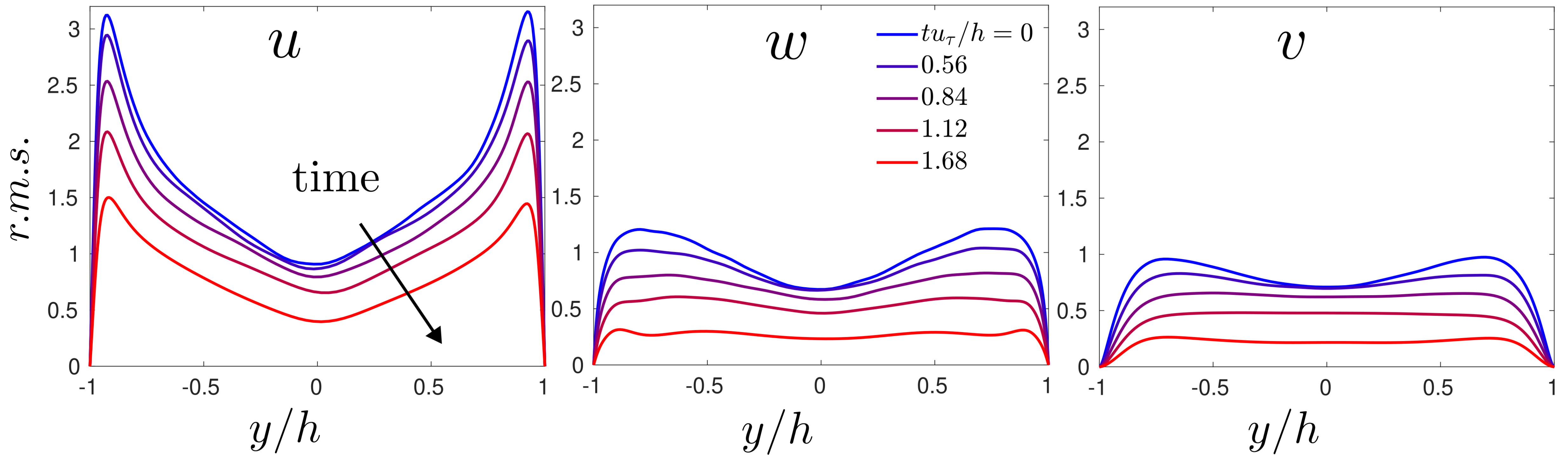


Ensemble Forecast



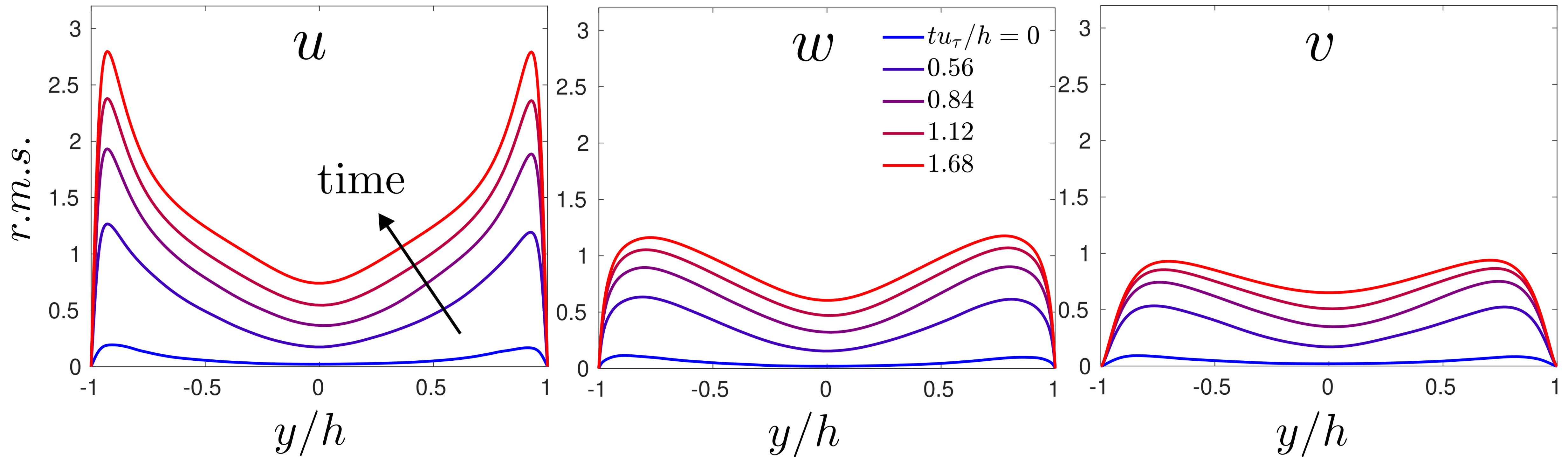
Predictable energy

r.m.s. of the ensemble-averaged velocity fluctuations



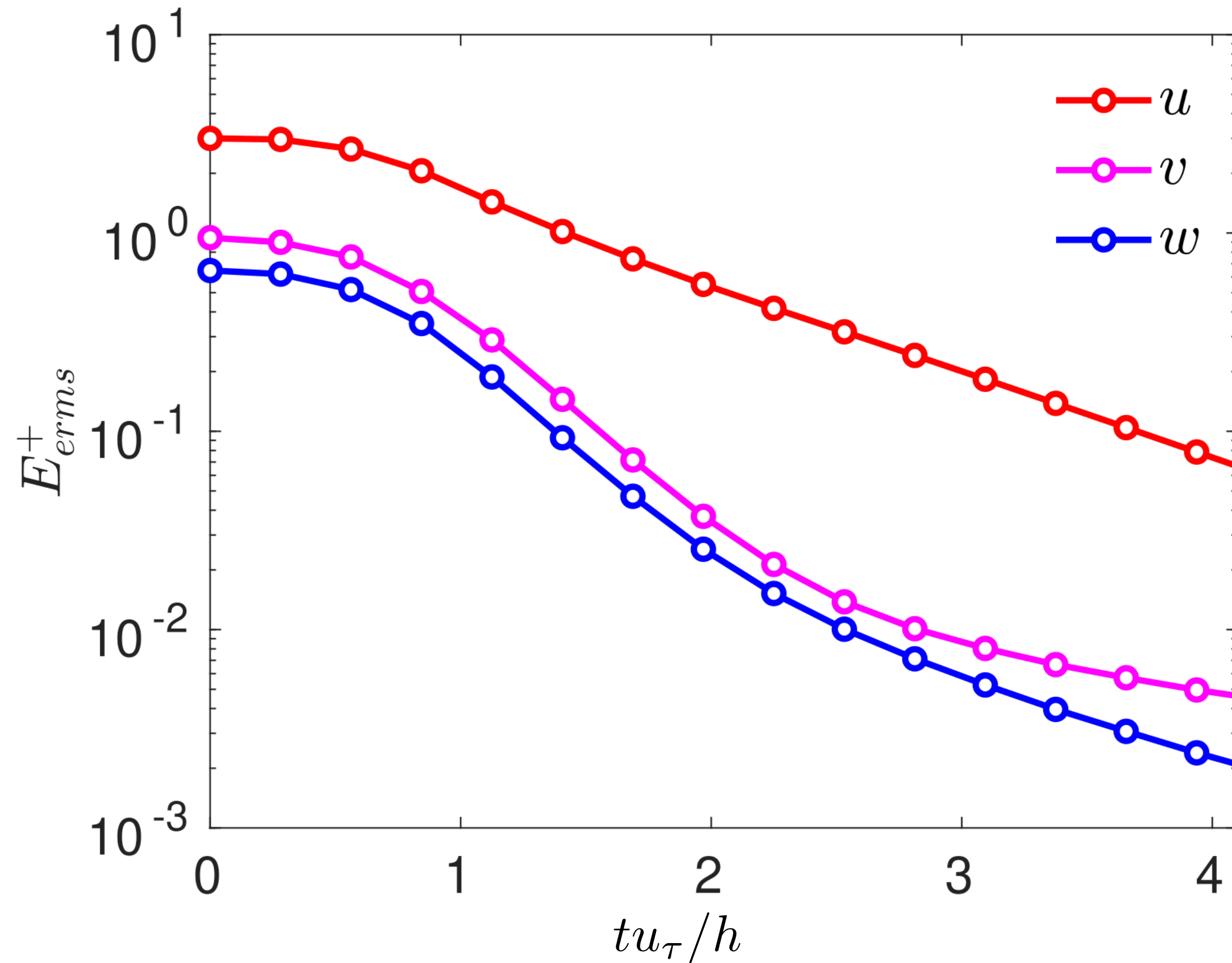
Uncertainty growth (Unpredictable energy)

Ensemble standard deviation of the velocity fluctuations

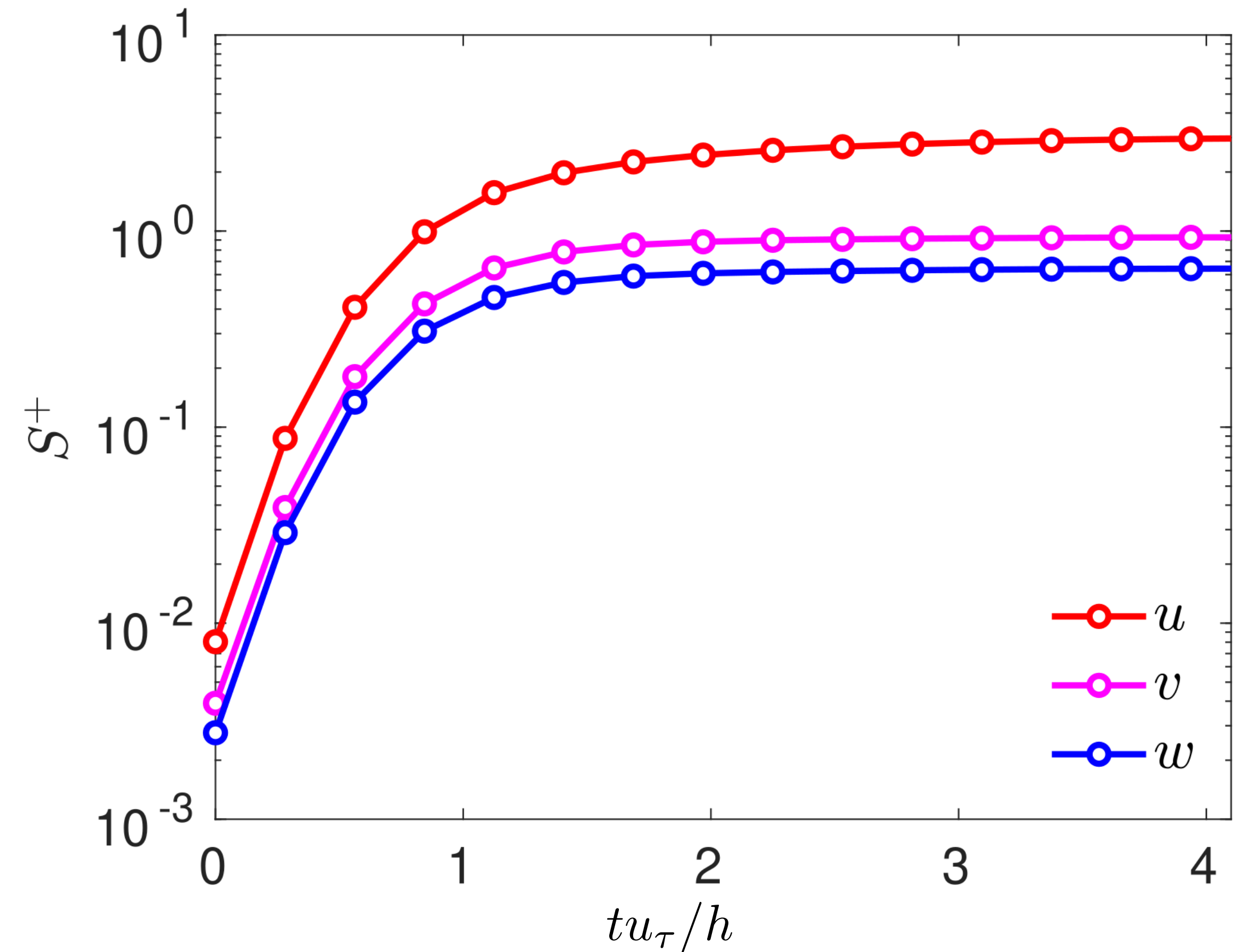


Predictable energy vs uncertainty

Energy of the ensemble averaged fluctuations



Ensemble-**variance** of the velocity fluctuations

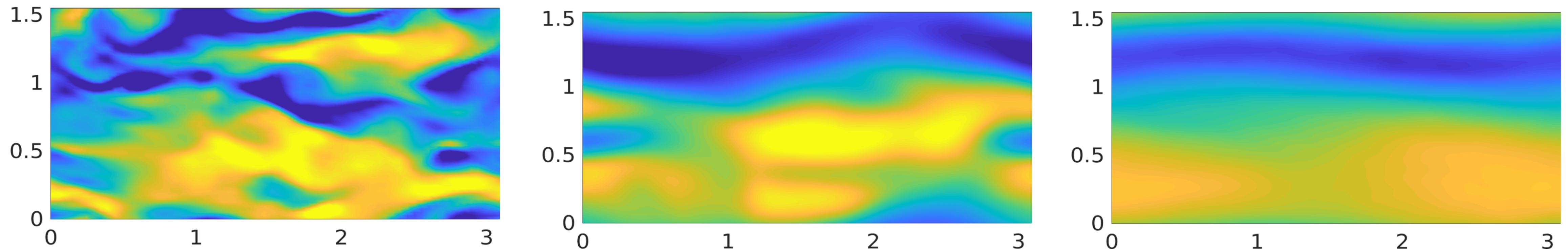


Modelling uncertainty growth

TARGET: Affordable predictability/uncertainty calculations

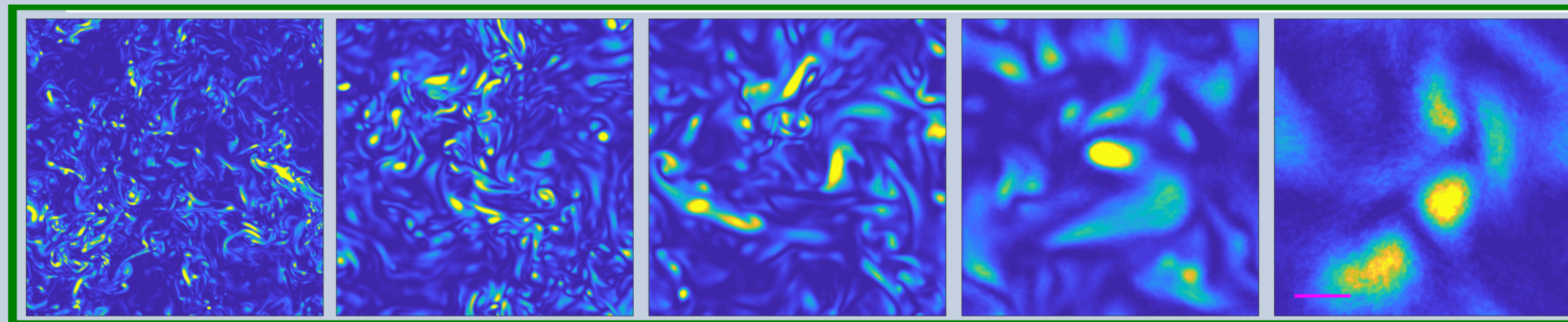
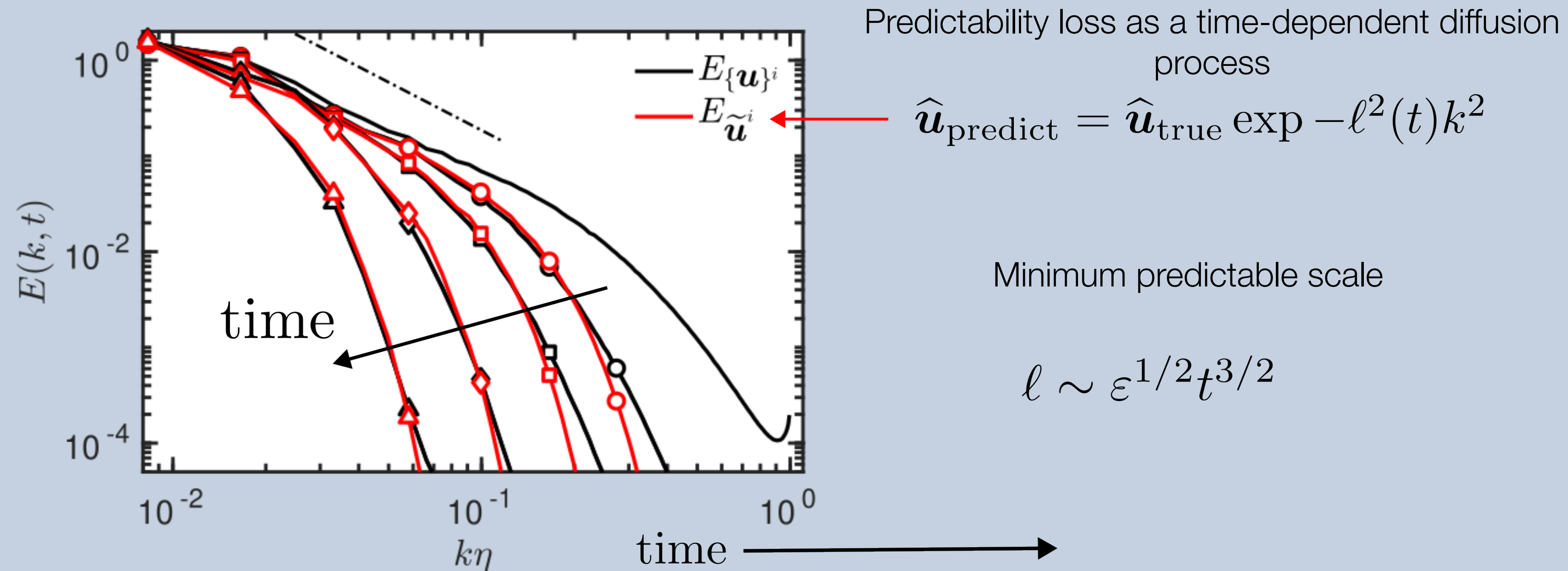
- Study the scaling of perturbation growth
- Is there a relatively simple model for uncertainty growth?

Uncertainty $\approx f(\text{Time})$



A simpler case: HIT

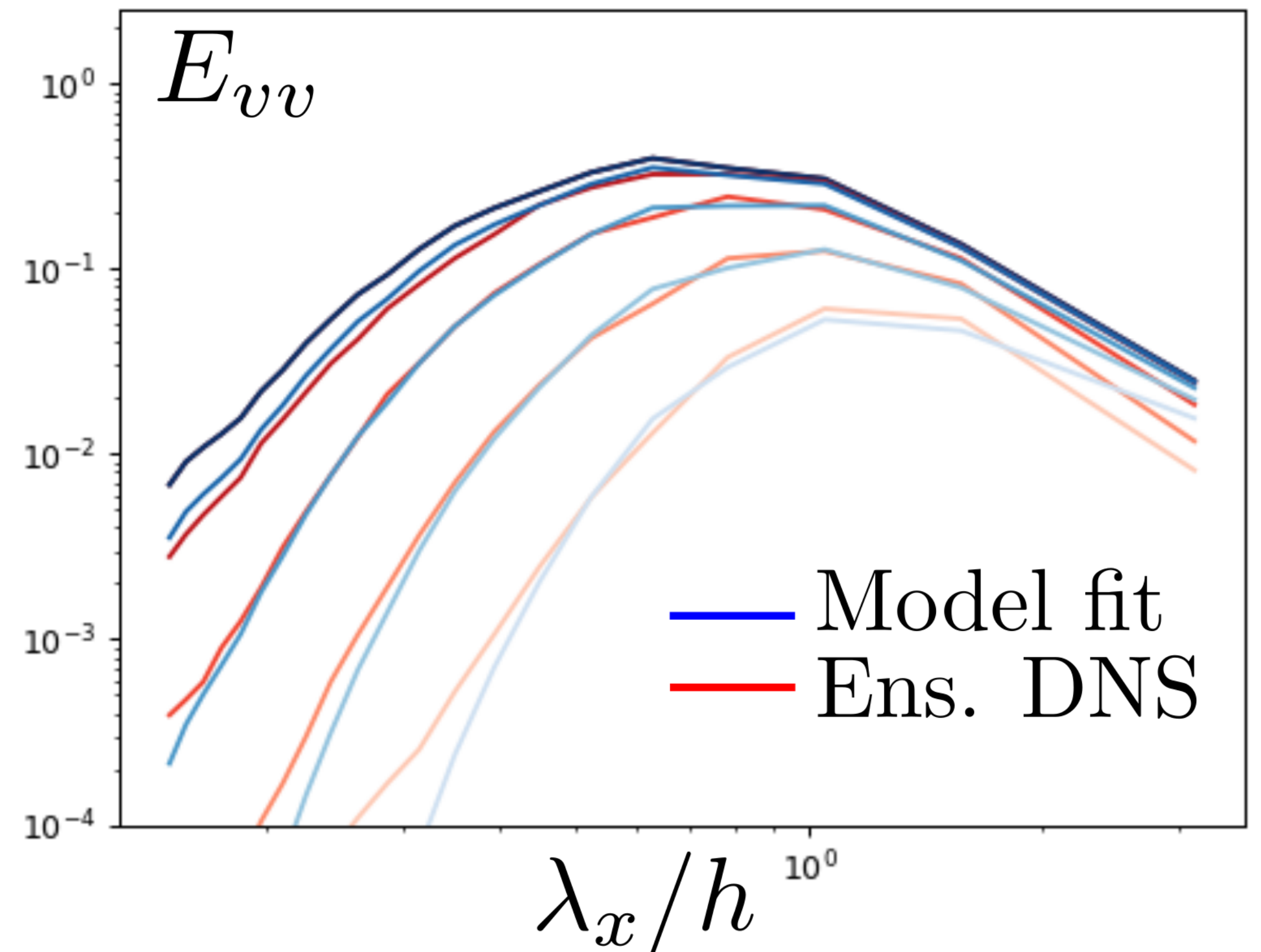
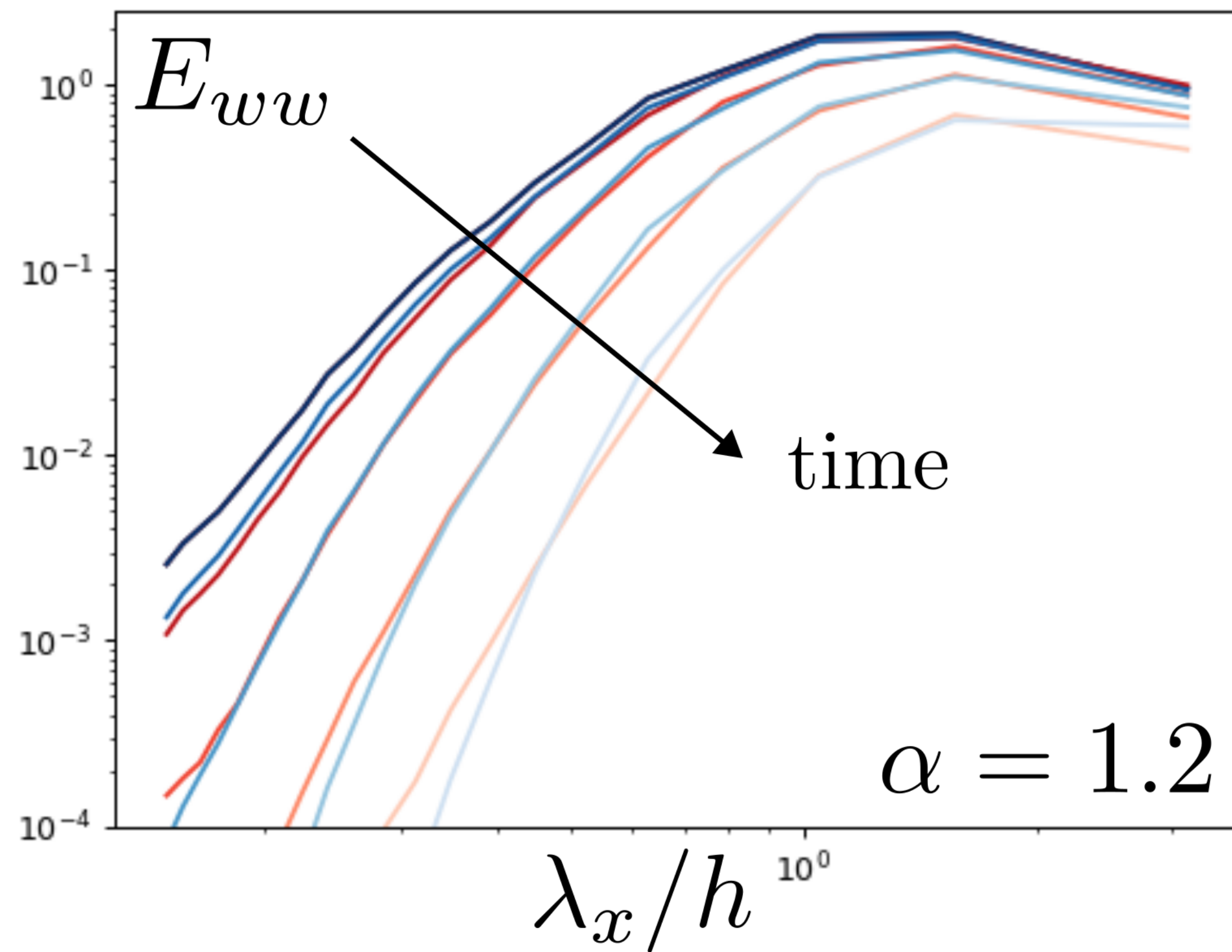
Uncertainty growth in isotropic turbulence



Predictability loss in channel flow

Cross-plane velocity components — Close to the wall

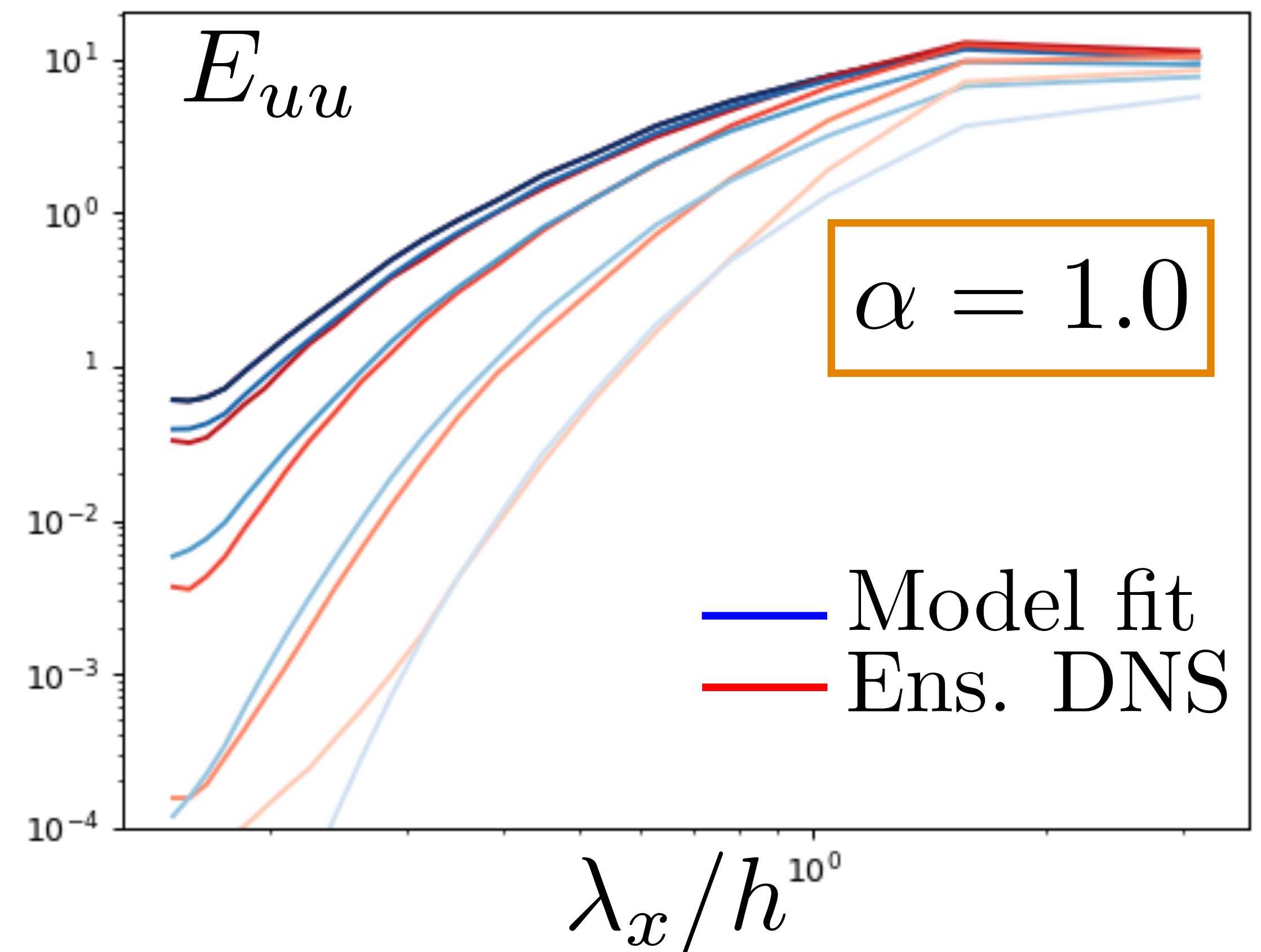
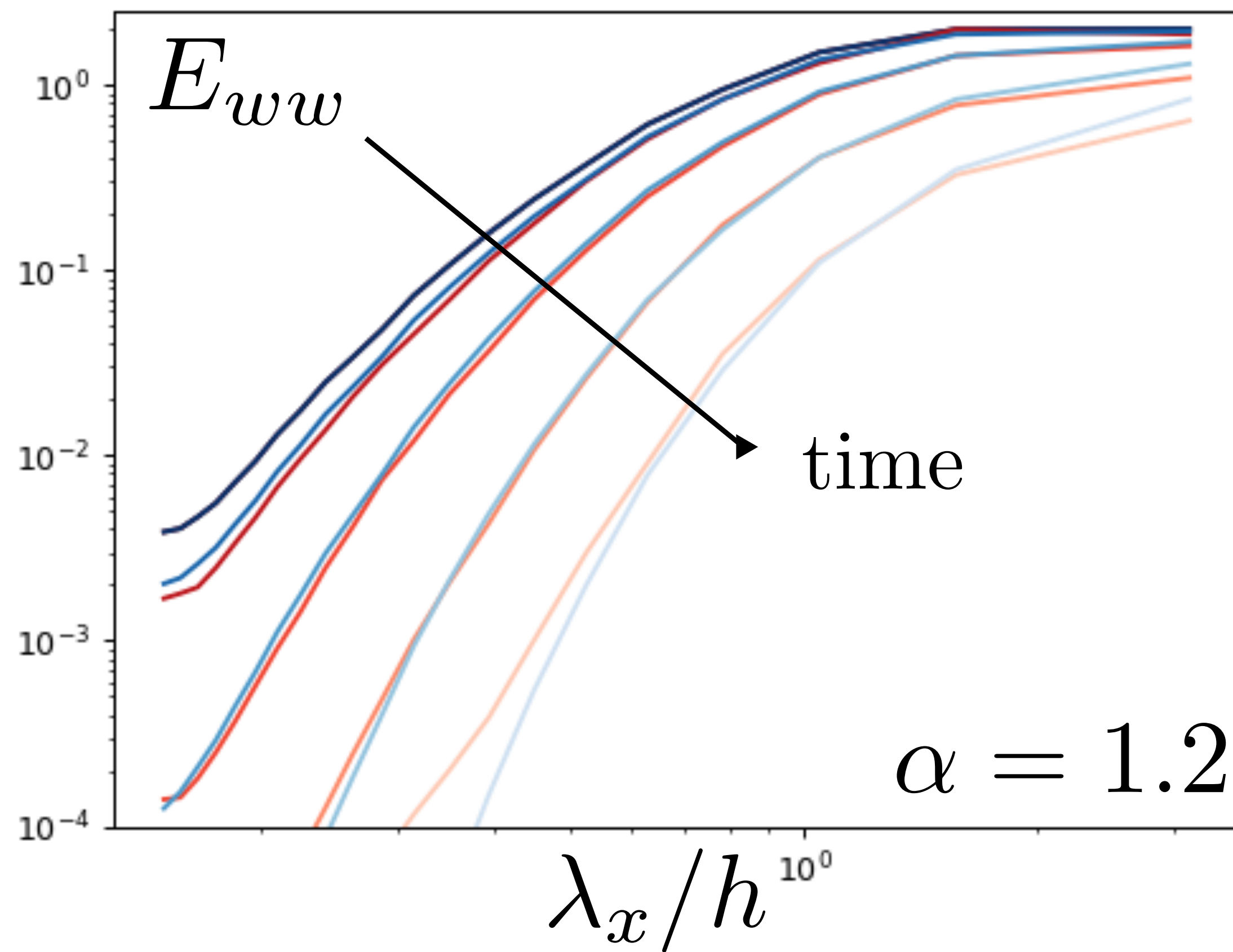
$$y^+ = 10 \quad \hat{\mathbf{u}}_{\text{predict}} = \hat{\mathbf{u}}_{\text{true}} \exp -\ell^\alpha |k_x|^\alpha$$



Predictability loss in channel flow

The **streamwise** velocity component is **different**

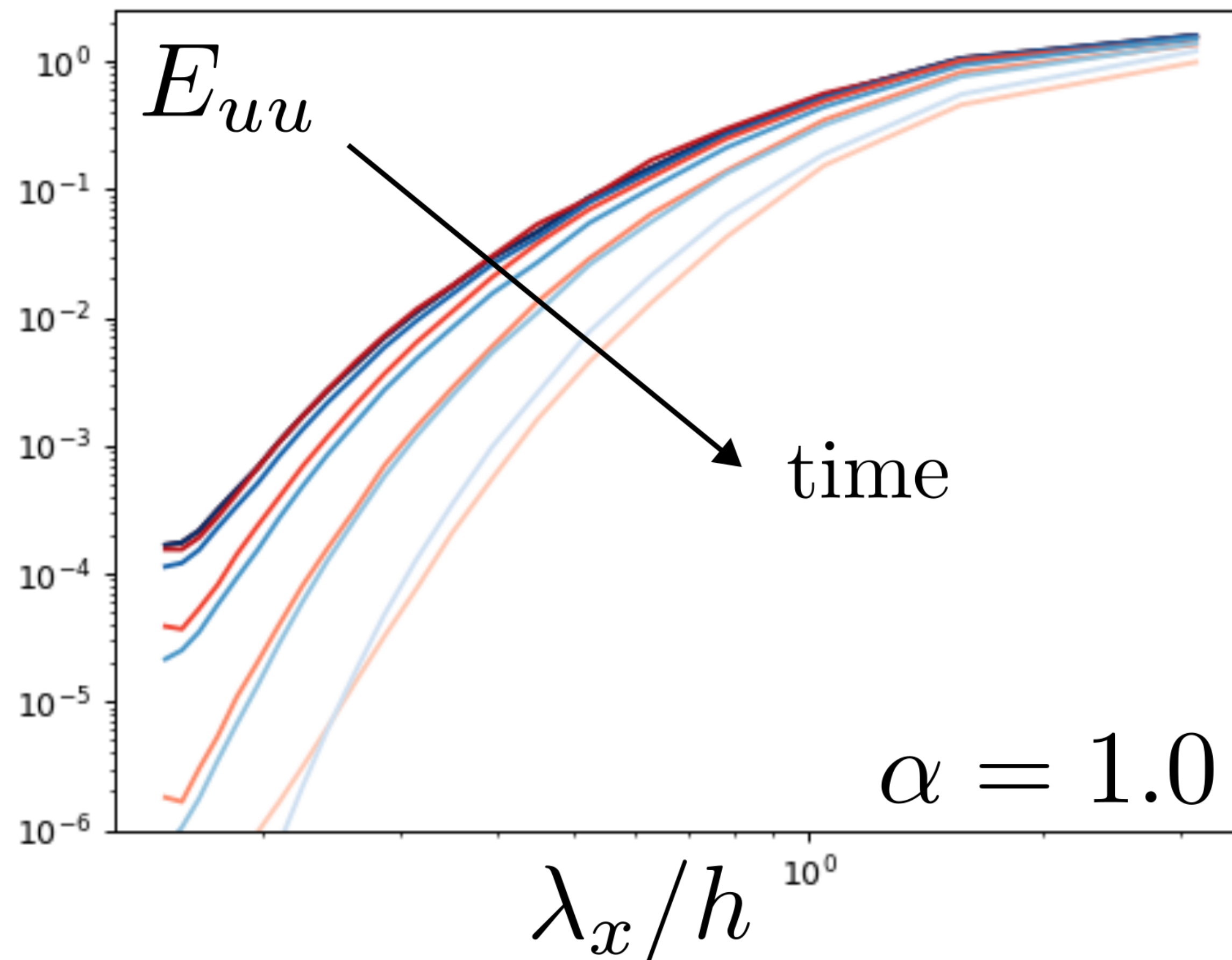
$$y^+ = 32 \quad \hat{\mathbf{u}}_{\text{predict}} = \hat{\mathbf{u}}_{\text{true}} \exp -\ell^\alpha |k_x|^\alpha$$



Predictability loss in channel flow

The anomaly exponents α are consistent towards the channel centreline

$$y = h \quad \hat{\mathbf{u}}_{\text{predict}} = \hat{\mathbf{u}}_{\text{true}} \exp -\ell^\alpha |k_x|^\alpha$$



Conclusions and Future Work

- **Predictability loss** in wall-bounded flows seems to be well described by **anomalous diffusion** ($\alpha \neq 2$) with a **time-dependent diffusion coefficient**
- This diffusion is **different** for the streamwise and the cross-plane velocities. The source of the anomaly must be the **shear**...

- Similarities with **LES modelling**,

$$\begin{aligned}\partial_t \{u_i\} + \{u_j\} \partial_j \{u_i\} &= -\partial_i \{p\} + \partial_j \tau_{ij} + \{f_i\}, \\ \partial_i \{u_i\} &= 0,\end{aligned}$$

$$\tau_{ij} = \{u_i\} \{u_j\} - \{u_i u_j\}$$

- **Potential** — DNS-informed control with uncertainty
— LES models from optimal prediction over the uncertain (subgrid) scales

Conclusions and Future Work

- **Predictability loss** in wall-bounded flows seems to be well described by **anomalous diffusion** ($\alpha \neq 2$) with a **time-dependent diffusion coefficient**

- This diffusion is **different** for the streamwise and the cross-plane velocities. The source of the anomaly must be the near-wall region.

Thanks for listening!

- Similarities with **LES modelling**,

$$\begin{aligned}\partial_t \{u_i\} + \{u_j\} \partial_j \{u_i\} &= -\partial_i \{p\} + \partial_j \tau_{ij} + \{f_i\}, \\ \partial_i \{u_i\} &= 0,\end{aligned}$$

$$\tau_{ij} = \{u_i\} \{u_j\} - \{u_i u_j\}$$

Questions?

- **Potential**

DNS-informed control with uncertainty

LES models from optimal prediction over the uncertain (subgrid) scales